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CAMEX-2 EDOP Reprocessed Dataset Documentation

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1. Introduction

This document provides relevant information for the reprocessed ER-2 Doppler Radar (EDOP) data collected during the Second Convection and Moisture Experiment (CAMEX-2), which took place in August 1995. The CAMEX series of field campaign focused on expanding our understanding of dynamics and thermodynamics of tropical deep convection, including tropical cyclones.

EDOP is an X-band (9.6 GHz) Doppler radar built and maintained by NASA Goddard Space Flight Center that flew aboard the NASA ER-2 aircraft during several field campaigns that took place between 1993 through 2007. At the time of this campaign, EDOP was fitted with a log receiver for the reflectivity channels, which would later be replaced with a linear receiver after CAMEX-2; the Doppler channels used a linear receiver throughout the instrument lifetime. The EDOP instrument mounts both a nadir-pointing antenna and a forward-angled antenna, both of which are located in the nose of the ER-2. During CAMEX-2, the forward antenna pointed at approximately 33.2° forward of nadir. Alongside EDOP, the ER-2 payload for CAMEX-2 also included AMPR, MIR, MAMS, and LIP. The table below provides a quick reference for the radar characteristics during CAMEX-2:

EDOP Characteristics			
Frequency	9.60 GHz	Beamwidth	2.9°
Peak Power	25 kW	Nadir surface footprint	1.1 km diameter
Duty Cycle	0.44% max	Forward antenna tilt	33.2°
Pulse Width	0.25, 0.5, 1.0 µs	Nyquist Velocity	34 m s^{-1}
PRF	2200 Hz, 4400 Hz	Gate Spacing	37.5 m

The current reprocessing efforts are limited to the previously processed data files and did not delve into reprocessing the data from the raw files. Below is a list of flights during which EDOP successfully collected data:

Flight Date	EDOP File Times (UTC)	Description of Flight
17 July 1995	17:10 – 17:13	Test flight over central Pennsylvania
23 August 1995	20:29 – 20:33	SSMI under flight
25 August 1995	14:15 – 14:17, 14:18 – 14:19, 14:25 – 14:29, 15:16 – 15:19	TS Jerry
26 August 1995	21:22 – 21:26, 21:31 – 21:35, 21:45 – 21:49, 21:50 – 21:52, 21:55 – 22:02, 22:03 – 22:03, 22:08 – 22:19, 22:19 – 22:20, 22:27 – 22:37, 22:47 – 22:56	Terrestrial convection over South Carolina
28 August 1995	22:00 – 22:04, 22:03 – 22:13, 23:01 – 23:04, 23:06 – 23:09, 23:21 – 23:25, 23:31 – 23:35, 23:40 – 23:47	Oceanic convection off the coast of the southeastern United States

2. Reprocessing Methods

The data file used to produce the L1B reprocessed files were the Universal Format (UF) binary files containing the publicly available processed data. The processing applied to produce these original files included computing reflectivity and Doppler velocity from the raw moments data as well as removing the aircraft motion from the Doppler velocity and calibrating the reflectivity values. For two files (22:27 – 22:37 26 August 1995 and 23:06 – 23:09 28 August 1995), this also included computing the spectrum width. The additional work performed as part of the modern reprocessing effort was to remove the effects of non-uniform beam filling (NUBF) from the Doppler velocities and to package the data in a netcdf4 format, complete with meta data. While the data collected by the nadir and forward-angled antenna are stored in separate files, the time stamps for data from each antenna are matched such that the pair of files will contain the exact same time stamps.

For a nadir-pointing beam, the effect of NUBF on the Doppler velocity is to produce an apparent upward motion where reflectivity increases in the along-track direction and an apparent downward motion where reflectivity decreases in the along-track direction. As such, the NUBF correction for the nadir antenna data set is a function of the along-track gradient in reflectivity. For the forward-angled antenna, however, the vertical gradient in reflectivity must also be considered. The equation we use for computing the NUBF correction, v_N is as follows:

$$v_N = v_P \frac{\beta^2 R \ln(10)}{160 \ln(2)} \left(\nabla_y(dBZ_e) \cos^2 \phi_0 + \nabla_z(dBZ_e) \cos \phi_0 \sin \phi_0\right),$$

where v_P is the aircraft ground speed, y is oriented in the along-track direction, z is oriented in the vertical (positive upwards), β is the angular beam width in radians, ϕ_0 is the along-track angle of the beam center from nadir, R is the range from the antenna (positive away from the antenna), and dBZ_e is the reflectivity in logarithmic units. Note, for the nadir-pointing antenna, the vertical reflectivity gradient term drops out. For CAMEX-2, we computed the along-track

gradient using a convolution of the kernel $[-1, 0, 0, 0, 1]$, which covers two seconds of data collection, and the along-beam gradient using a convolution of the kernel $[-1, 0, 0, 0, 0, 0, 1]$. The vertical reflectivity gradient can then be computed by the following equation:

$$\nabla_z(dBZ_e) = \frac{\nabla_y(dBZ_e)\sin\phi_0 - \nabla_B(dBZ_e)}{\cos\phi_0},$$

where $\nabla_B(dBZ_e)$ is the along-beam gradient (positive away from the antenna).

Additionally, because time stamps were stored with integer seconds and EDOP recorded data twice per second, a time correction was applied. For each pair of identical time stamps in the record, the time correction add 0.5 seconds to the latter of the pair. 0.5 seconds is added to the initial time only if the initial time is unique (i.e., the file record starts on what would have been the latter time step of a pair had the file started earlier). Occasionally, there are more than the two expected duplicates. We first attempt to fit all the data into the time line at no greater than 0.5 second intervals. In instances where there is no way to fit all the data into the timeline without resorting to sub-half second intervals, we simply spread the data points linearly in time.

3. Known Issues

1. Lack of noise estimate – The EDOP receiver used a log detector during the CAMEX-2 field campaign. As such, we did not estimate the noise level (our noise estimations assume the noise was recorded in linear space). Instead, we use a power threshold of -120 dBm to mask the data arrays.
2. Invalid velocity – Doppler velocity issues invalidate some or all of the velocity data in the following files:

File	Details
CAMEX-2_EDOP_Forward_Antenna_199508282306_199508282309.nc	<<1 minute period
CAMEX-2_EDOP_Forward_Antenna_199508282321_199508282325.nc	Entire file
CAMEX-2_EDOP_Forward_Antenna_199508282331_199508282335.nc	Entire file
CAMEX-2_EDOP_Forward_Antenna_199508282340_199508282347.nc	Entire file

   This issue only appears to affect the forward-angle antenna files; the matching nadir antenna files appear to be unaffected.
3. Forward beam has questionable velocities for the 17 July 1995 flight.

4. Change Log

The following is a record of changes that occurred in each version of this data set, listed in reverse chronological order such that the most recent data version is at the top.

RevA	Made correction to forward-antenna NUBF correction and added some missing metadata.
Rev-	Initial release of reprocessed data files.

5. Netcdf4 Format

The following is a copy of the output of ncdump -h for the nadir and forward-angle 23:06 – 23:09 28 August 1995 files:

5.1 Nadir antenna file

netcdf CAMEX2_EDOP_Nadir_L1B_RevA_199508282306_199508282309 {

// global attributes:
:Title = "Level1B processed EDOP airborne Doppler radar nadir antenna data collected during CAMEX-2" ;
:Institution = "NASA Goddard Space Flight Center, Mesoscale Atmospheric Processes Lab (Code 612), High Altitude Radar Group" ;
:Radar = "EDOP" ;
:AntennaDescriptor = "Nadir Antenna" ;
:Aircraft = "NASA ER-2" ;
:Experiment = "CAMEX-2" ;
:FlightID = "95-185 " ;
:FlightDate = "19950828" ;
:FlightLegName = "" ;
:FlightLegCode = "" ;
:ExperimentPI = "" ;
:InstrumentPI = "Gerald M. Heymsfield, NASA/GSFC" ;
:DataContacts = "Charles N. Helms, UMD/ESSIC & NASA/GSFC, charles.n.helms@nasa.gov; Matthew L. Walker McLinden, NASA/GSFC, matthew.l.mclinden@nasa.gov" ;
:Rawdata_filename = "28aug95-2306.bin" ;
:UFfilename = "950828_2306.uf,950828_2306_hybrid.uf,950828_2306_sw.uf" ;
:UFprocessDate = "27/09/95" ;
:UFlastModificationDate = "27/09/95" ;
:L1B_processDate = "2025-04-03 19:01:36.733420+00:00" ;
:L1B_revision = "RevA" ;
:L1B_revisionNote = "Made correction to forward-antenna NUBF correction and added some missing metadata. Please reach out to the data contacts with any questions or concerns regarding the data." ;
:L1B_revisionHistory = "Revision History:\nRevA :: Made correction to forward-antenna NUBF correction and added some missing metadata.\nRev- :: Initial release of the reprocessed CAMEX-2 data.\nRevDraft :: Preliminary processed file. Subject to change." ;
:NavigationSource = "ER-2 aircraft GPS/INS Hybrid with altitude taken from ER-2 GPS" ;
:AirfieldName = "Wallops Island, VA, USA" ;
:AirfieldLatitude = 37.56f ;
:AirfieldLongitude = -75.27f ;
:TiltFromNadir_degrees = -0.86f ;
:AzimuthFromHeading_degrees = 0.f ;
:GateSpacing_m = 75.f ;
:PulseWidth_Hz = 0.5f ;
:PRF_Hz = 2200.f, 4400.f ;

:PRT_usec = 454.5f, 227.3f ;
:NyquistVelocity_m_s-1 = 34.2f ;
:ReflIntegrationTime_sec = 0.5f ;
:DopIntegrationTime_sec = 0.5f ;
:RadarConstant_dB = 91.38f ;
:IFbandwidth_MHz = 2.f ;
:Frequency_GHz = 9.6f ;
:Wavelength_cm = 3.109375f ;
:Beamwidth_degrees = 2.97f ;
:TransmitPower_dBm = 69.f ;
:ReceiverBandwidth_MHz = 2.f ;
:TransmitRecievePolarization = "VV" ;
:ReceiverGain_dB = 0.f ;
:PeakPower_dBmW = 69.f ;
:AntennaGain_dB = 36.1f ;
:PulseLength_usec = 0.32f ;
:UFdumpFilename = "CAMEX2_EDOP_UFdump_950828_2306.nc" ;

group: Products {
dimensions:
Range = 300 ;
TimeUTC = 361 ;
variables:
float Range(Range) ;
Range:_FillValue = NaNf ;
Range:correctionFromUF_meters = 250.f ;
Range:units = "meters" ;
Range:description = "Along-beam range in meters from antenna" ;
double TimeUTC(TimeUTC) ;
TimeUTC:_FillValue = NaN ;
TimeUTC:source = "Aircraft INS time" ;
TimeUTC:units = "seconds since 1970-01-01 00:00 UTC" ;
TimeUTC:correctionFromUF_seconds = 0.f ;
TimeUTC:description = "UTC profile time in unix epoch format (seconds since 00 UTC 1 January 1970)" ;
float dBZeCoPol(Range, TimeUTC) ;
dBZeCoPol:_FillValue = NaNf ;
dBZeCoPol:UF_fieldName = "ZN" ;
dBZeCoPol:description = "Equivalent reflectivity factor in dB for the co-polarization channel" ;
dBZeCoPol:units = "10*log10(mm^6/m^3)" ;
dBZeCoPol:calibration_constant_dB = 0.f ;
float VelocityCorrectedCoPol(Range, TimeUTC) ;
VelocityCorrectedCoPol:_FillValue = NaNf ;
VelocityCorrectedCoPol:description = "Co-polarization channel Doppler velocity corrected to account for both non-uniform beam filling and aircraft motion. Note, the MaskCoPol mask is applied during the NUBF correction." ;
VelocityCorrectedCoPol:units = "m/s" ;
VelocityCorrectedCoPol:signConvention = "Away from antenna is positive" ;

```
        VelocityCorrectedCoPol:equation = "VelocityCorrected = VelocityUncorrected +
DopplerCorrectionNUBF" ;
    float VelocityUncorrectedCoPol(Range, TimeUTC) ;
        VelocityUncorrectedCoPol:_FillValue = NaNf ;
        VelocityUncorrectedCoPol:description = "Co-polarization channel Doppler velocity with only
the aircraft motion correction applied" ;
        VelocityUncorrectedCoPol:units = "m/s" ;
        VelocityUncorrectedCoPol:signConvention = "Away from antenna is positive" ;
        VelocityUncorrectedCoPol:equation = "VelocityCorrected = VelocityUncorrected +
DopplerCorrectionNUBF" ;
        VelocityUncorrectedCoPol:UF_fieldName = "VN" ;
    float PowerCoPol(Range, TimeUTC) ;
        PowerCoPol:_FillValue = NaNf ;
        PowerCoPol:description = "Recieved power for the co-polarization channel" ;
        PowerCoPol:units = "dBm" ;
        PowerCoPol:UF_fieldname = "MN" ;
    float SpectrumWidthCoPol(Range, TimeUTC) ;
        SpectrumWidthCoPol:UFfilename = "950828_2306_sw.uf" ;
        SpectrumWidthCoPol:_FillValue = NaNf ;
        SpectrumWidthCoPol:description = "Doppler spectrum width estimate for the co-polarization
channel" ;
        SpectrumWidthCoPol:units = "m/s" ;
        SpectrumWidthCoPol:UF_fieldname = "WN" ;
    float CN(Range, TimeUTC) ;
        CN:_FillValue = NaNf ;
        CN:description = "Co-polarization channel raw power counts" ;
        CN:UFfieldname = "CN" ;
 } // group Products

group: Information {
 dimensions:
    Range = 300 ;
    TimeUTC = 361 ;
 variables:
    byte MaskCoPol(Range, TimeUTC) ;
        MaskCoPol:description = "Mask for removing noise.  Noise was set to a missing value in original
data, so mask is generated based on that missing value." ;
        MaskCoPol:key = "0 = Signal, 1 = Noise" ;
    byte MaskSfcCh(Range, TimeUTC) ;
        MaskSfcCh:description = "Mask for removing noise.  Noise was set to a missing value in original
data, so mask is generated based on that missing value." ;
        MaskSfcCh:key = "0 = Signal, 1 = Noise" ;
    short OceanGateIndex(TimeUTC) ;
        OceanGateIndex:_FillValue = 0s ;
        OceanGateIndex:description = "Range index of gate at expected zero altitude above mean sea
level based on radar geometry and aircraft attitude." ;
    float DopplerCorrectionAircraftMotion(TimeUTC) ;
        DopplerCorrectionAircraftMotion:_FillValue = NaNf ;
```

```
        DopplerCorrectionAircraftMotion:description = "Estimated aircraft motion correction to
Doppler velocity" ;
        DopplerCorrectionAircraftMotion:units = "m/s" ;
        DopplerCorrectionAircraftMotion:note = "Correction is already applied to both
VelocityCorrected and VelocityUncorrected" ;
    float DopplerCorrectionCoPolNUBF(Range, TimeUTC) ;
        DopplerCorrectionCoPolNUBF:_FillValue = NaNf ;
        DopplerCorrectionCoPolNUBF:description = "Estimated non-uniform beam filling correction to
co-polarization channel Doppler velocity accounting for horizontal reflectivity gradients" ;
        DopplerCorrectionCoPolNUBF:units = "m/s" ;
        DopplerCorrectionCoPolNUBF:horizontalGradientKernal = -1s, 0s, 0s, 0s, 1s ;
        DopplerCorrectionCoPolNUBF:note = "Correction is already applied to VelocityCorrected" ;
    float dxdr(TimeUTC) ;
        dxdr:_FillValue = NaNf ;
        dxdr:description = "Data cross-track distance from aircraft per unit range" ;
        dxdr:units = "m/m" ;
        dxdr:convention = "Positive is in the starboard direction" ;
    float dydr(TimeUTC) ;
        dydr:_FillValue = NaNf ;
        dydr:description = "Data along-track distance from aircraft per unit range" ;
        dydr:units = "m/m" ;
        dydr:convention = "Positive is in the direction of aircraft travel" ;
    float dzdr(TimeUTC) ;
        dzdr:_FillValue = NaNf ;
        dzdr:description = "Data vertical distance from aircraft per unit range" ;
        dzdr:units = "m/m" ;
        dzdr:convention = "Positive is in the upward direction" ;
    float horizontalResolution6dB(Range) ;
        horizontalResolution6dB:_FillValue = NaNf ;
        horizontalResolution6dB:description = "Approximate horizontal resolution defined as width of
spatial weighting after averaging as a function of radar range" ;
        horizontalResolution6dB:units = "meters" ;
 } // group Information

group: Navigation {
 dimensions:
    TimeUTC = 361 ;
 variables:
    float NominalDistance(TimeUTC) ;
        NominalDistance:_FillValue = NaNf ;
        NominalDistance:description = "Nominal aircraft travel distance estimated by cumulatively
summing the instantaneous velocities" ;
        NominalDistance:units = "meters" ;
        NominalDistance:source = "TimeUTC and GroundSpeed" ;
    float Latitude(TimeUTC) ;
        Latitude:_FillValue = NaNf ;
        Latitude:description = "Latitude" ;
        Latitude:units = "degreesNorth" ;
```

```
    float Longitude(TimeUTC) ;
        Longitude:_FillValue = NaNf ;
        Longitude:description = "Longitude" ;
        Longitude:units = "degreesEast" ;
    float Altitude(TimeUTC) ;
        Altitude:_FillValue = NaNf ;
        Altitude:description = "Aircraft height above sea level" ;
        Altitude:units = "meters" ;
    float GroundSpeed(TimeUTC) ;
        GroundSpeed:_FillValue = NaNf ;
        GroundSpeed:description = "Aircraft total horizontal speed" ;
        GroundSpeed:units = "m/s" ;
    float NorthVelocity(TimeUTC) ;
        NorthVelocity:_FillValue = NaNf ;
        NorthVelocity:description = "Aircraft northward component of velocity" ;
        NorthVelocity:units = "m/s" ;
    float EastVelocity(TimeUTC) ;
        EastVelocity:_FillValue = NaNf ;
        EastVelocity:description = "Aircraft eastward component of velocity" ;
        EastVelocity:units = "m/s" ;
    float UpVelocity(TimeUTC) ;
        UpVelocity:_FillValue = NaNf ;
        UpVelocity:description = "Aircraft upward component of velocity" ;
        UpVelocity:units = "m/s" ;
    float Track(TimeUTC) ;
        Track:_FillValue = NaNf ;
        Track:description = "Direction of motion in degrees from north with 90 degrees indicating
eastward motion" ;
        Track:units = "degrees" ;
    float Heading(TimeUTC) ;
        Heading:_FillValue = NaNf ;
        Heading:description = "Direction towards which aircraft nose is pointing in degrees from north
with 90 degrees indicating eastward pointing" ;
        Heading:units = "degrees" ;
        Heading:correctionFromUF_degrees = 0.f ;
    float Drift(TimeUTC) ;
        Drift:_FillValue = NaNf ;
        Drift:description = "Difference between track and heading" ;
        Drift:units = "degrees" ;
        Drift:equation = "Drift = Track - Heading" ;
    float Roll(TimeUTC) ;
        Roll:_FillValue = NaNf ;
        Roll:description = "Roll about along-aircraft axis.  Positive values correspond to the starboard
(right) wing dipping" ;
        Roll:units = "degrees" ;
        Roll:correctionFromUF_degrees = 0.f ;
    float Pitch(TimeUTC) ;
        Pitch:_FillValue = NaNf ;
```

```
        Pitch:units = "degrees" ;
        Pitch:description = "Pitch about across-aircraft axis.  Positive values correspond to a nose up
position" ;
        Pitch:correctionFromUF_degrees = 0.f ;
    float VerticalAcceleration(TimeUTC) ;
        VerticalAcceleration:_FillValue = NaNf ;
        VerticalAcceleration:units = "m/s/s" ;
        VerticalAcceleration:description = "Vertical acceleration of aircraft" ;
    float FlightLevelWindDirection(TimeUTC) ;
        FlightLevelWindDirection:_FillValue = NaNf ;
        FlightLevelWindDirection:description = "Observed wind direction at flight level" ;
        FlightLevelWindDirection:units = "degrees" ;
        FlightLevelWindDirection:source = "INS" ;
    float FlightLevelWindSpeed(TimeUTC) ;
        FlightLevelWindSpeed:_FillValue = NaNf ;
        FlightLevelWindSpeed:description = "Observed wind speed at flight level" ;
        FlightLevelWindSpeed:units = "m/s" ;
        FlightLevelWindSpeed:source = "INS" ;
 } // group Navigation
}
```

5.2 Forward-angle Antenna File

```
netcdf CAMEX2_EDOP_Forward_L1B_RevA_199508282306_199508282309 {

// global attributes:
        :Title = "Level1B processed EDOP airborne Doppler radar forward antenna data collected during
CAMEX-2" ;
        :Institution = "NASA Goddard Space Flight Center, Mesoscale Atmospheric Processes Lab (Code
612), High Altitude Radar Group" ;
        :Radar = "EDOP" ;
        :AntennaDescriptor = "Forward Antenna" ;
        :Aircraft = "NASA ER-2" ;
        :Experiment = "CAMEX-2" ;
        :FlightID = "95-185  " ;
        :FlightDate = "19950828" ;
        :FlightLegName = "" ;
        :FlightLegCode = "" ;
        :ExperimentPI = "" ;
        :InstrumentPI = "Gerald M. Heymsfield, NASA/GSFC" ;
        :DataContacts = "Charles N. Helms, UMD/ESSIC & NASA/GSFC, charles.n.helms@nasa.gov;
Matthew L. Walker McLinden, NASA/GSFC, matthew.l.mclinden@nasa.gov" ;
        :Rawdata_filename = "28aug95-2306.bin" ;
        :UFfilename = "950828_2306.uf,950828_2306_hybrid.uf,950828_2306_sw.uf" ;
        :UFprocessDate = "27/09/95" ;
        :UFlastModificationDate = "27/09/95" ;
        :L1B_processDate = "2025-04-03 19:01:36.741900+00:00" ;
```

:L1B_revision = "RevA" ;
:L1B_revisionNote = "Made correction to forward-antenna NUBF correction and added some missing metadata. Please reach out to the data contacts with any questions or concerns regarding the data." ;
:L1B_revisionHistory = "Revision History:\nRevA :: Made correction to forward-antenna NUBF correction and added some missing metadata.\nRev- :: Initial release of the reprocessed CAMEX-2 data.\nRevDraft :: Preliminary processed file. Subject to change." ;
:NavigationSource = "ER-2 aircraft GPS/INS Hybrid with altitude taken from ER-2 GPS" ;
:AirfieldName = "Wallops Island, VA, USA" ;
:AirfieldLatitude = 37.56f ;
:AirfieldLongitude = -75.27f ;
:TiltFromNadir_degrees = 33.2f ;
:AzimuthFromHeading_degrees = 0.f ;
:GateSpacing_m = 75.f ;
:PulseWidth_Hz = 0.5f ;
:PRF_Hz = 2200LL, 4400LL ;
:PRT_usec = 454.5, 227.3 ;
:NyquistVelocity_m_s-1 = 34.2f ;
:ReflIntegrationTime_sec = 0.5f ;
:DopIntegrationTime_sec = 0.5f ;
:RadarConstant_dB = 94.03f ;
:IFbandwidth_MHz = 2.f ;
:Frequency_GHz = 9.6f ;
:Wavelength_cm = 3.109375f ;
:Beamwidth_degrees = 2.97f ;
:TransmitPower_dBm = 68.59f ;
:ReceiverBandwidth_MHz = 2.f ;
:TransmitRecievePolarization = "VV" ;
:ReceiverGain_dB = 0.f ;
:PeakPower_dBmW = 68.59f ;
:AntennaGain_dB = 35.f ;
:PulseLength_usec = 0.32f ;
:UFdumpFilename = "CAMEX2_EDOP_UFdump_950828_2306.nc" ;

group: Products {
 dimensions:
  TimeUTC = 361 ;
  Range = 300 ;
 variables:
  double TimeUTC(TimeUTC) ;
   TimeUTC:_FillValue = NaN ;
   TimeUTC:source = "Aircraft INS time" ;
   TimeUTC:units = "seconds since 1970-01-01 00:00 UTC" ;
   TimeUTC:correctionFromUF_seconds = 0.f ;
   TimeUTC:description = "UTC profile time in unix epoch format (seconds since 00 UTC 1 January 1970)" ;
  float Range(Range) ;
   Range:_FillValue = NaNf ;

Range:correctionFromUF_meters = 300.f ;
Range:units = "meters" ;
Range:description = "Along-beam range in meters from antenna" ;
float dBZeCoPol(Range, TimeUTC) ;
dBZeCoPol:_FillValue = NaNf ;
dBZeCoPol:description = "Equivalent reflectivity factor in dB for the co-polarization channel" ;
dBZeCoPol:units = "10*log10(mm^6/m^3)" ;
dBZeCoPol:calibration_constant_dB = 0.f ;
dBZeCoPol:UF_fieldName = "ZF" ;
float VelocityCorrectedCoPol(Range, TimeUTC) ;
VelocityCorrectedCoPol:description = "Co-polarization channel Doppler velocity corrected to account for both non-uniform beam filling and aircraft motion. Note, the MaskCoPol mask is applied during the NUBF correction." ;
VelocityCorrectedCoPol:signConvention = "Away from antenna is positive" ;
VelocityCorrectedCoPol:equation = "VelocityCorrected = VelocityUncorrected + DopplerCorrectionNUBF" ;
VelocityCorrectedCoPol:_FillValue = NaNf ;
VelocityCorrectedCoPol:units = "m/s" ;
float VelocityUncorrectedCoPol(Range, TimeUTC) ;
VelocityUncorrectedCoPol:_FillValue = NaNf ;
VelocityUncorrectedCoPol:description = "Co-polarization channel Doppler velocity with only the aircraft motion correction applied" ;
VelocityUncorrectedCoPol:units = "m/s" ;
VelocityUncorrectedCoPol:signConvention = "Away from antenna is positive" ;
VelocityUncorrectedCoPol:equation = "VelocityCorrected = VelocityUncorrected + DopplerCorrectionNUBF" ;
VelocityUncorrectedCoPol:UF_fieldName = "VF" ;
float PowerCoPol(Range, TimeUTC) ;
PowerCoPol:_FillValue = NaNf ;
PowerCoPol:description = "Recieved power for the co-polarization channel" ;
PowerCoPol:units = "dBm" ;
PowerCoPol:UF_fieldname = "MF" ;
float PowerCrPol(Range, TimeUTC) ;
PowerCrPol:_FillValue = NaNf ;
PowerCrPol:description = "Recieved power for the cross-polarization channel" ;
PowerCrPol:units = "dBm" ;
PowerCrPol:gateShift_gates = 0LL ;
PowerCrPol:UF_fieldname = "MX" ;
float SpectrumWidthCoPol(Range, TimeUTC) ;
SpectrumWidthCoPol:_FillValue = NaNf ;
SpectrumWidthCoPol:description = "Doppler spectrum width estimate for the co-polarization channel" ;
SpectrumWidthCoPol:units = "m/s" ;
SpectrumWidthCoPol:UF_fieldname = "WF" ;
SpectrumWidthCoPol:UFfilename = "950828_2306_sw.uf" ;
float CF(Range, TimeUTC) ;
CF:description = "Co-polarization channel raw power counts" ;
CF:UFfieldname = "CF" ;

```
        CF:_FillValue = NaNf ;
    float CX(Range, TimeUTC) ;
        CX:_FillValue = NaNf ;
 } // group Products

group: Information {
 dimensions:
    Range = 300 ;
    TimeUTC = 361 ;
 variables:
    byte MaskCoPol(Range, TimeUTC) ;
        MaskCoPol:description = "Mask for removing noise.  Noise was set to a missing value in original
data, so mask is generated based on that missing value." ;
        MaskCoPol:key = "0 = Signal, 1 = Noise" ;
    byte MaskCrPol(Range, TimeUTC) ;
        MaskCrPol:description = "Mask for removing noise.  Noise was set to a missing value in original
data, so mask is generated based on that missing value." ;
        MaskCrPol:key = "0 = Signal, 1 = Noise" ;
    short OceanGateIndex(TimeUTC) ;
        OceanGateIndex:_FillValue = 0s ;
        OceanGateIndex:description = "Range index of gate at expected zero altitude above mean sea
level based on radar geometry and aircraft attitude." ;
    float DopplerCorrectionAircraftMotion(TimeUTC) ;
        DopplerCorrectionAircraftMotion:_FillValue = NaNf ;
        DopplerCorrectionAircraftMotion:description = "Estimated aircraft motion correction to
Doppler velocity" ;
        DopplerCorrectionAircraftMotion:units = "m/s" ;
        DopplerCorrectionAircraftMotion:note = "Correction is already applied to both
VelocityCorrected and VelocityUncorrected" ;
    float DopplerCorrectionCoPolNUBF(Range, TimeUTC) ;
        DopplerCorrectionCoPolNUBF:_FillValue = NaNf ;
        DopplerCorrectionCoPolNUBF:description = "Estimated non-uniform beam filling correction to
co-polarizontaion channel Doppler velocity accounting for both horizontal and vertical reflectivity
gradients" ;
        DopplerCorrectionCoPolNUBF:units = "m/s" ;
        DopplerCorrectionCoPolNUBF:horizontalGradientKernal = -1s, 0s, 0s, 0s, 1s ;
        DopplerCorrectionCoPolNUBF:alongBeamGradientKernal = -1s, 0s, 0s, 0s, 0s, 0s, 1s ;
        DopplerCorrectionCoPolNUBF:note = "Correction is already applied to VelocityCorrected" ;
    float dxdr(TimeUTC) ;
        dxdr:_FillValue = NaNf ;
        dxdr:description = "Data cross-track distance from aircraft per unit range" ;
        dxdr:units = "m/m" ;
        dxdr:convention = "Positive is in the starboard direction" ;
    float dydr(TimeUTC) ;
        dydr:_FillValue = NaNf ;
        dydr:description = "Data along-track distance from aircraft per unit range" ;
        dydr:units = "m/m" ;
        dydr:convention = "Positive is in the direction of aircraft travel" ;
```

```
    float dzdr(TimeUTC) ;
        dzdr:_FillValue = NaNf ;
        dzdr:description = "Data vertical distance from aircraft per unit range" ;
        dzdr:units = "m/m" ;
        dzdr:convention = "Positive is in the upward direction" ;
    float horizontalResolution6dB(Range) ;
        horizontalResolution6dB:_FillValue = NaNf ;
        horizontalResolution6dB:description = "Approximate horizontal resolution defined as width of
spatial weighting after averaging as a function of radar range" ;
        horizontalResolution6dB:units = "meters" ;
  } // group Information

group: Navigation {
  dimensions:
    TimeUTC = 361 ;
  variables:
    float NominalDistance(TimeUTC) ;
        NominalDistance:_FillValue = NaNf ;
        NominalDistance:description = "Nominal aircraft travel distance estimated by cumulatively
summing the instantaneous velocities" ;
        NominalDistance:units = "meters" ;
        NominalDistance:source = "TimeUTC and GroundSpeed" ;
    float Latitude(TimeUTC) ;
        Latitude:_FillValue = NaNf ;
        Latitude:description = "Latitude" ;
        Latitude:units = "degreesNorth" ;
    float Longitude(TimeUTC) ;
        Longitude:_FillValue = NaNf ;
        Longitude:description = "Longitude" ;
        Longitude:units = "degreesEast" ;
    float Altitude(TimeUTC) ;
        Altitude:_FillValue = NaNf ;
        Altitude:description = "Aircraft height above sea level" ;
        Altitude:units = "meters" ;
    float GroundSpeed(TimeUTC) ;
        GroundSpeed:_FillValue = NaNf ;
        GroundSpeed:description = "Aircraft total horizontal speed" ;
        GroundSpeed:units = "m/s" ;
    float NorthVelocity(TimeUTC) ;
        NorthVelocity:_FillValue = NaNf ;
        NorthVelocity:description = "Aircraft northward component of velocity" ;
        NorthVelocity:units = "m/s" ;
    float EastVelocity(TimeUTC) ;
        EastVelocity:_FillValue = NaNf ;
        EastVelocity:description = "Aircraft eastward component of velocity" ;
        EastVelocity:units = "m/s" ;
    float UpVelocity(TimeUTC) ;
        UpVelocity:_FillValue = NaNf ;
```

```
        UpVelocity:description = "Aircraft upward component of velocity" ;
        UpVelocity:units = "m/s" ;
    float Track(TimeUTC) ;
        Track:_FillValue = NaNf ;
        Track:description = "Direction of motion in degrees from north with 90 degrees indicating
eastward motion" ;
        Track:units = "degrees" ;
    float Heading(TimeUTC) ;
        Heading:_FillValue = NaNf ;
        Heading:description = "Direction towards which aircraft nose is pointing in degrees from north
with 90 degrees indicating eastward pointing" ;
        Heading:units = "degrees" ;
        Heading:correctionFromUF_degrees = 0.f ;
    float Drift(TimeUTC) ;
        Drift:_FillValue = NaNf ;
        Drift:description = "Difference between track and heading" ;
        Drift:units = "degrees" ;
        Drift:equation = "Drift = Track - Heading" ;
    float Roll(TimeUTC) ;
        Roll:_FillValue = NaNf ;
        Roll:description = "Roll about along-aircraft axis.  Positive values correspond to the starboard
(right) wing dipping" ;
        Roll:units = "degrees" ;
        Roll:correctionFromUF_degrees = 0.f ;
    float Pitch(TimeUTC) ;
        Pitch:_FillValue = NaNf ;
        Pitch:units = "degrees" ;
        Pitch:description = "Pitch about across-aircraft axis.  Positive values correspond to a nose up
position" ;
        Pitch:correctionFromUF_degrees = 0.f ;
    float VerticalAcceleration(TimeUTC) ;
        VerticalAcceleration:_FillValue = NaNf ;
        VerticalAcceleration:units = "m/s/s" ;
        VerticalAcceleration:description = "Vertical acceleration of aircraft" ;
    float FlightLevelWindDirection(TimeUTC) ;
        FlightLevelWindDirection:_FillValue = NaNf ;
        FlightLevelWindDirection:description = "Observed wind direction at flight level" ;
        FlightLevelWindDirection:units = "degrees" ;
        FlightLevelWindDirection:source = "INS" ;
    float FlightLevelWindSpeed(TimeUTC) ;
        FlightLevelWindSpeed:_FillValue = NaNf ;
        FlightLevelWindSpeed:description = "Observed wind speed at flight level" ;
        FlightLevelWindSpeed:units = "m/s" ;
        FlightLevelWindSpeed:source = "INS" ;
  } // group Navigation
}
```